Introduction

Photoactivation localization microscopy (PALM) and stochastic optical reconstruction microscopy (STORM) enable localization of fluorescent molecules with nanometric resolution (Betzig et al., 2006; Hess et al., 2006; Rust et al., 2006). The localization precision in these single molecule localization techniques is highly dependent on the number of detected photons (Thomson et al., 2002; Clouvel et al., 2013), so maximizing the number of detected photons in these methods is essential. One way to measure this quality is in fact the shape of the Point Spread Function (PSF). The optical components inside the microscope (the high numerical aperture objective, various lenses and dichroic mirrors) and the refractive index mismatch between the immersion oil of the objective and the water based biological sample induce aberrations, which negatively alter the PSF. In addition, depending on the protocol of cell fixation, the biological sample can also induce a pattern of aberrations (Schwertner et al., 2007; Simmonds et al., 2011), even in the first few hundreds of nanometers from the coverslip. Aberrations affect the symmetry of the PSF in all three dimensions by redistributing the photons from the focal spot to the periphery of the PSF and this way affecting the localization precision (Clouvel et al., 2013).

To compensate for these aberrations, Imagine Optic developed the adaptive optics device MicAO 3DSR, specifically designed for 3D PALM/STORM imaging, which can be easily implemented on any inverted frame microscope. Aberrations are detected using image-based modal iterative algorithms (Débarre et al., 2007; Facomprez et al., 2012) that are simple to use with the integrated MicAO software. The continuous membrane deformable mirror (Mirao 52e) inside MicAO 3DSR is used to correct these aberrations with exceptional precision. After the correction of the PSF, the number of detected photons can be almost doubled (Clouvel et al., 2013), which leads to significantly improved localization precision in single molecule localization methods (figure 1A and B).

In addition to improved localization precision, MicAO also enables three-dimensional imaging using an astigmatic approach similar to the method based on adding a cylindrical lens (Huang et al., 2008). With its deformable mirror, MicAO introduces a tunable amount of perfect astigmatism, free of any residual aberrations (Izeddin et al., 2012). An astigmatic PSF is axially asymmetric, extending in one lateral direction above the focus and in another direction below the focus (figure 1C). The difference between the extension in the X and Y directions reveals how far from the focus the emitter is located. A calibration curve can be generated by recording a Z stack of a diffraction limited point source, for example a small fluorescent bead (smaller than 200nm), and fitting the X and Y widths of the PSF along the Z axis (figure 1D). The most important factor of a high quality calibration curve is the difference between the X and Y width, which ideally forms a straight line (the upper panel of the calibration curve; figure 1D). The slope of this line is indicative of the Z localization precision, which can be tuned by the amount of astigmatism applied by the deformable mirror – the bigger the amplitude of astigmatism, the steeper the slope, and thus the more precise Z localization.

The model sample

As a model of water based sample, we used 200nm fluorescent beads embedded in 2% agarose gel (98% water). Here we show an example z-profile of a 200nm fluorescent bead imaged at 22µm depth (figure 2A). The image-based iterative algorithm (3N) using the deformable...
mirror corrected for 165nm RMS of spherical aberration, whereas amplitudes of all other Zernike modes were small and therefore could be neglected. After the correction, the fluorescence intensity in the focal plane was almost doubled, the PSF diameter along the Z axis decreased by 50% (the full width half maximum changed from 1639nm to 1172nm) and a symmetrical shape of the PSF above and below the focus was achieved (figure 2B).

An astigmatic approach is completely unusable deeper than 5µm without adaptive correction because the spherical aberration significantly affects the calibration curve due to its axial asymmetry and loss of light. For visualization of this behavior we applied 90nm RMS of astigmatism on the deformable mirror without correcting depth-induced aberrations and imaged the bead at 22µm depth (figure 3A). It can be clearly seen from figure 3A that now the PSF is highly perturbed compared to the PSF on the surface (figure 1). This is especially clear from the calibration curve (figure 3B), which becomes completely asymmetrical, reducing the difference between X and Y extensions of the PSF (the upper panel of figure 3B). However, correction of aberrations completely restores the axial symmetry. As seen in figure 3C, when we corrected for 165nm RMS of spherical aberration and applied 90nm RMS of astigmatism, the PSF became laterally extended as needed above and below the focus, and the resulting calibration curve is perfectly symmetrical.

**3D PALM imaging**

To demonstrate the feasibility of the astigmatic approach with a deformable mirror for deep 3D PALM/STORM imaging, we used HeLa cells stably expressing the conjugate of mEos2 and centrin1 – one of the proteins from the centrosome complex (Sillibourne et al., 2011). Earlier we performed 3D 2-color PALM/dSTORM imaging of two centrosomal proteins, centrin-1 and Cep164 in the close vicinity from the coverslip (Clouvel et al., 2013) where we determined the 3D composition of these two proteins with 7nm lateral and 13nm axial localization precision. To perform the 3D deep PALM imaging, we constructed a sample composed of fixed HeLa cells expressing the conjugate of mEos2-centrin1 (kindly provided by James Sillibourne and Michel Bornens, UMR144, Institut Curie, France) embedded in 2% agarose gel at different depths. We also added 100nm fluorescent beads for two purposes: to monitor the lateral and axial drift and to determine the required depth-dependent aberration correction using the 3N algorithm. Here we show the results of PALM imaging at a depth of 50µm. After the correction of aberrations at this depth, we introduced 130nm RMS of astigmatism and acquired the calibration curve (figure 4, right). The slope of this calibration curve is similar to that obtained at the

![Figure 3](image-url)
surface of the coverslip, therefore the Z localization precision at 50µm depth is actually comparable to the localization precision on the surface of the coverslip. For the lateral position determination we fitted images with a 2D Gaussian function using an algorithm based on a modified Multi Target Tracking (MTT) algorithm (Sergé et al., 2008) as it was described previously (Izeddin et al., 2012). Figure 4 shows the reconstructed image of the centrin-1 at 50µm depth. In order to minimize the Z drift we acquired only 3000 frames (1777 localizations) compared to 20000 images taken on the surface (11020 localizations) and the residual Z drift was corrected during the data treatment. The average number of photons was about 500 photons per detection. According to the localization precision dependence on the number of detected photons and to the value of the calibration curve slope (Clouvel et al., 2013), the localization precision of this experiment is 13nm laterally and 25nm axially. The precision of the reconstructed structure can also be judged from the size of centrin1 cluster, which is roughly the same as on the surface: the diameter is 100 to 150nm in X and Y and 200nm in Z.

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References


